# Derivation of Chebyshev Differentiation Matrix

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### 1 Lagrange interpolation polynomial

Consider the set of  $u(x_j)$  for the discrete points  $\{x_j\}, j = 0, ..., N$ . The interpolation polynomial for  $u(x_j)$  in the Lagrange form is

$$p(x) = \sum_{j=0}^{N} \phi_j(x) u(x_j)$$
 (1)

where  $\phi_j(x)$  is called Lagrange interpolation coefficient and is defined by

$$\phi_j(x) = \prod_{\substack{m=0\\j\neq m}}^N \left(\frac{x-x_m}{x_j-x_m}\right).$$
(2)

Lagrange interpolation (1) is also defined as follows

$$\phi_j(x) = \frac{S_N(x)}{S'_N(x_j)(x - x_j)},$$
(3)

where  $S_N(x)$  is defined by

$$S_N(x) = \prod_{j=0}^{N} (x - x_j).$$
 (4)

## 2 Chebyshev interpolation

Chebyshev polynomial is defined by

$$T_n(x) = \cos(n\theta), \quad x = \cos\theta.$$
 (5)

For the  $S_N(x)$  in the interpolation polynomial (3), we choose the following form

$$S_N(x) = (1 - x^2) \frac{\mathrm{d}T_N(x)}{\mathrm{d}x}.$$
 (6)

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By using the Chebyshev polynomial (5), we can expand  $S_N(x)$  as follows:

$$S_N(x) = (1 - x^2) \frac{\mathrm{d}T_N(x)}{\mathrm{d}x} = \sin^2 \theta \frac{-N\sin n\theta}{-\sin \theta} = N\sin \theta \sin N\theta, \quad (7)$$

so that  $S_N(x)$  becomes zero for

$$N\theta = \pi j, \quad j : \text{integer.}$$

Therefore we define

$$\theta_j = \frac{\pi j}{N}, \quad j = 0, 1, \cdots, N, \tag{8}$$

then we get

$$S_N(x_j) = 0, \quad x_j = \cos\frac{\pi j}{N}.$$

Here  $x_j$  are the Gauss-Chebyshev-Lobatto points. Thus, using (6) and Chebyshev polynomial (5), interpolation coefficient (3) is defined by

$$\phi_j(x) = \frac{(1-x^2)\frac{\mathrm{d}T_N(x)}{\mathrm{d}x}}{d_j(x-x_j)}, \quad j = 0, 1, \cdots, N,$$
(9)

where  $d_j$  are

$$d_j = S'_N(x_j) = -c_j N^2 T_N(x_j), \quad ' \equiv \frac{\mathrm{d}}{\mathrm{d}x}$$
(10)

and

$$c_j = 2$$
, for  $j = 0, N$ ,  $c_j = 1$  for  $0 < j < N$ . (11)

(Proof) Derivative of  $S_N(x)$  with x is

$$S'_N(x) = -N \frac{\cos \theta}{\sin \theta} \sin N\theta - N^2 \cos N\theta$$

Here for  $j = 1, \dots, N-1$ ,  $\sin \theta_j \neq 0$  and  $\sin N\theta_j = 0$ , so that we obtain  $S'_N(x_j) = -N^2 T_N(x_j)$ . While  $\sin \theta_j = 0$  and  $\sin N \times \theta_j = 0$  for j = 0, N. Therefore  $S'_N$  includes 0/0, so that we apply the L'Hopital theorem for the first term of the right hand side

$$S'_{N}(x_{j}) = S'_{N}(\theta = 0 \text{ or } \pi) = -N \frac{\cos \theta}{\sin \theta} \sin N\theta - N^{2} \cos N\theta$$
$$\stackrel{\text{L'Hopital}}{=} -N \frac{-\sin \theta \sin N\theta + N \cos \theta \cos N\theta}{\cos \theta} - N^{2} \cos N\theta = -2N^{2}T_{N}(x_{j})$$

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#### **3** Derivation of Chebyshev differentiation matrix

Consider Gauss-Chebyshev-Lobatto points (or Chebyshev points, for short) in the  $x \in [-1, 1]$  defined by

$$x_j = \cos \theta_j = \frac{\pi j}{N}, \quad j = 0, 1, \cdots, N.$$
(12)

Given a grid function u defined on the Chebyshev points, we obtain a discrete derivative w in two steps:

Let p be the unique polynomial of degree ≤ N with p(x<sub>j</sub>) = u<sub>j</sub>, 0 ≤ j ≤ N.
Set w<sub>j</sub> = p'(x<sub>j</sub>).

This operation is linear, so it can be represented by multiplication by an  $(N+1) \times (N+1)$  matrix, which we shall denote by  $D_N$ :

$$w_i = (D_N)_{ij}\psi_j \tag{13}$$

Here N is an arbitrary positive integer, even or odd. And,  $(D_N)_{ij}$  represents the (i, j) elements of the matrix  $D_N$ .

In order to derive the matrix  $D_N$ , consider the interpolation polynomial (1) and the interpolation coefficients (9). From the derivative  $dp(x)/dx = u(x_j)d\phi_j(x)/dx$  we get

$$(D_N)_{ij} = \frac{1}{d_j} \left[ \frac{\mathrm{d}}{\mathrm{d}x} \phi_j(x) \right]_{x=x_i}.$$
 (14)

Considering eqn. (9) we obtain

$$\frac{\mathrm{d}}{\mathrm{d}x}\phi_j(x) = \frac{1}{(x-x_j)^2} \left\{ \left[ -2x\frac{\mathrm{d}}{\mathrm{d}x}T_N(x) + (1-x^2)\frac{\mathrm{d}^2}{\mathrm{d}x^2}T_N(x) \right] (x-x_j) - (1-x^2)\frac{\mathrm{d}}{\mathrm{d}x}T_N(x) \right\}, \quad j = 0, 1, \cdots, N.$$
(15)

(I) Non-diagonal elements : 1 < i < N, 1 < j < N,  $i \neq j$ if we put  $x = x_i$  in eqn.(15), we obtain

$$(D_N)_{ij} = \frac{1}{d_j} \frac{1}{x_i - x_j} (1 - x_i^2) \frac{\mathrm{d}^2}{\mathrm{d}x^2} T_N(x_i), \tag{16}$$

where we used the relation  $-2x_i dT_N(x_i)/dx = 0$  in the bracket []. That is  $\theta_i = i\pi/N$ ,  $\sin \theta_i \neq 0$ 

$$-2x\frac{\mathrm{d}}{\mathrm{d}x}T_N(x)\bigg|_{x=x_i} = -2\cos\theta_i\frac{-N\sin i\pi}{-\sin\theta_i} = 0$$

Similarly this relation was applied for the second term of the ordinary differential equation of Chebyshev polynomial

$$(1 - x^2)\frac{\mathrm{d}^2}{\mathrm{d}x^2}T_n(x) - x\frac{\mathrm{d}}{\mathrm{d}x}T_n(x) + n^2T_n(x) = 0, \qquad (17)$$

then we get the following relation:

$$(1 - x_i^2)\frac{\mathrm{d}^2}{\mathrm{d}x^2}T_N(x_i) = -N^2T_N(x_i).$$
 (18)

Substituting this into eqn.(16) we obtain

$$(D_N)_{ij} = \frac{d_i}{d_j} \frac{1}{x_i - x_j} = \frac{c_i}{c_j} \frac{T_N(x_i)}{T_N(x_j)} \frac{1}{x_i - x_j}.$$
(19)

Considering  $T_N(x_i) = \cos[N(i\pi)/N] = \cos i\pi = (-1)^i$  and (11), we get

$$(D_N)_{ij} = \frac{c_i}{c_j} \frac{(-1)^{i+j}}{x_i - x_j}, \quad c_i = \begin{cases} 2 & \text{for } i = 0 \text{ or } N\\ 1 & \text{otherwise} \end{cases}$$
(20)

(II) Diagonal elements (i = j) 0 < i, j < NWhen  $x \to x_j$ , the first derivative (15)

$$\frac{\mathrm{d}}{\mathrm{d}x}\phi_j(x)\Big|_{x\to x_j} = \frac{1}{(x-x_j)^2} \left\{ \left[Y(x)\right](x-x_j) - (1-x^2)\frac{\mathrm{d}}{\mathrm{d}x}T_N(x)\right\}\Big|_{x\to x_j}$$

becomes 0/0 because  $(1 - x_j^2) dT_N(x_j)/dx = 0$ . Where, we defined  $Y(x) = -2x dT_N(x_j)/dx + (1 - x^2) d^2T_N(x_j)/dx^2$ , while  $x \to x_j$ ,  $Y(x_j) \neq 0$ . We can apply the L'Hopital theorem to the above derivative and get

$$\frac{\mathrm{d}}{\mathrm{d}x}\phi_j(x)\Big|_{x\to x_j} = \frac{1}{2(x-x_j)} \left\{ -2xT'_N + (1-x^2)T''_N + (x-x_j)\left[-2T'_N - 2xT''_N - 2xT''_N + (1-x^2)T''_N\right] + 2xT'_N - (1-x^2)T''_N \right\}$$
$$= \frac{1}{2(x-x_j)} \left\{ (x-x_j)\left[ -2T'_N - 4xT''_N + (1-x^2)T''_N\right] \right\}$$
$$= \frac{1}{2} \left\{ -2T'_N - 4xT''_N + (1-x^2)T''_N \right\}, \tag{21}$$

so that the diagonal elements of the Chebyshev differentiation matrix are

$$(D_N)_{jj} = -\frac{1}{2d_j} \left\{ 2T'_N(x_j) + 4x_j T''_N(x_j) - (1 - x_j^2)T'''_N(x_j) \right\}.$$
 (22)

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Because of  $j \neq 0, N$ ,  $\sin \theta_j \neq 0$ , then  $T'_N(x_j) = 0$ . And from eqn. (17)

$$-(1-x^2)T_N'''(x) = -3xT_N''(x) + (N^2 - 1)T_N'(x).$$

Considering  $T'_N(x_j) = 0$ , we substitute this relation into eqn. (22) we obtain

$$(D_N)_{jj} = -\frac{1}{2d_j} x_j T_N''(x_j).$$

Moreover for  $T_N''(x_j)$  and making use of (18), the diagonal elements are derived as follows:

$$(D_N)_{jj} = -\frac{-x_j N^2 T_N(x_j)}{2d_j (1 - x_j^2)} = \frac{-x_j}{2(1 - x_j^2)}.$$
(23)

(III) i = 0, j = 0 or i = N, j = N

Because  $x_j = 1$  for j = 0 and  $x_j = -1$  for j = N, then the last term of the right hand side of (22) vanishes. And we know

$$T_N(1) = 1, \ T_N(-1) = (-1)^N, \ T'_N(1) = N^2, \ T'_N(-1) = -(-1)^N N^2$$

and also

$$T_N''(1) = \frac{(N^2 - 1)N^2}{3}, \quad T_N''(-1) = -(-1)^N \frac{(N^2 - 1)N^2}{3}.$$

Therfore the numerator and denominator of eqn.(22) are

$$i = 0, j = 0: \quad 2T'_N(1) + 4T''_N(1) = \frac{2N^2(2N^2 + 1)}{3}, \quad 2d_0 = -4N^2T_N(1)$$
$$i = N, j = N: \quad 2T'_N(-1) + 4T''_N(-1) = -(-1)^N\frac{2N^2(2N^2 + 1)}{3},$$
$$2d_0 = -4N^2T_N(-1),$$

so that finally we get

$$(D_N)_{00} = \frac{2N^2 + 1}{6}, \qquad (D_N)_{NN} = -\frac{2N^2 + 1}{6}.$$
 (24)

Derivation of  $T_N''(\pm 1)$ :

Ordinary differentiation equation for Chebyshev polynomial in (V) we used

$$-(1-x^2)T_N'''(x) = -3xT_N''(x) + (N^2 - 1)T_N'(x).$$

By using for x = 1 in above equation, we obtain

$$T_N''(1) = \frac{(N^2 - 1)}{3}T_N'(1) = \frac{(N^2 - 1)N^2}{3}.$$

For  $T_N''(-1)$ , we derive similarly.

### References

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- [3] Haydar Alici: Pseudospectral Methods for Differential Equations: Application to the Schrodinger Type Eigenvalue Problems, December 2003, The Middle East Technical University