

Derivation of Chebyshev Differentiation Matrix

Shigenobu Itoh

February 1, 2019

1 Lagrange interpolation polynomial

Consider the set of $u(x_j)$ for the discrete points $\{x_j\}$, $j = 0, \dots, N$. The interpolation polynomial for $u(x_j)$ in the Lagrange form is

$$p(x) = \sum_{j=0}^N \phi_j(x) u(x_j) \quad (1)$$

where $\phi_j(x)$ is called Lagrange interpolation coefficient and is defined by

$$\phi_j(x) = \prod_{\substack{m=0 \\ j \neq m}}^N \left(\frac{x - x_m}{x_j - x_m} \right). \quad (2)$$

Lagrange interpolation (1) is also defined as follows

$$\phi_j(x) = \frac{S_N(x)}{S'_N(x_j)(x - x_j)}, \quad (3)$$

where $S_N(x)$ is defined by

$$S_N(x) = \prod_{j=0}^N (x - x_j). \quad (4)$$

2 Chebyshev interpolation

Chebyshev polynomial is defined by

$$T_n(x) = \cos(n\theta), \quad x = \cos \theta. \quad (5)$$

For the $S_N(x)$ in the interpolation polynomial (3), we choose the following form

$$S_N(x) = (1 - x^2) \frac{dT_N(x)}{dx}. \quad (6)$$

By using the Chebyshev polynomial (5), we can expand $S_N(x)$ as follows:

$$S_N(x) = (1 - x^2) \frac{dT_N(x)}{dx} = \sin^2 \theta \frac{-N \sin n\theta}{-\sin \theta} = N \sin \theta \sin N\theta, \quad (7)$$

so that $S_N(x)$ becomes zero for

$$N\theta = \pi j, \quad j : \text{integer.}$$

Therefore we define

$$\theta_j = \frac{\pi j}{N}, \quad j = 0, 1, \dots, N, \quad (8)$$

then we get

$$S_N(x_j) = 0, \quad x_j = \cos \frac{\pi j}{N}.$$

Here x_j are the Gauss-Chebyshev-Lobatto points. Thus, using (6) and Chebyshev polynomial (5), interpolation coefficient (3) is defined by

$$\phi_j(x) = \frac{(1 - x^2) \frac{dT_N(x)}{dx}}{d_j(x - x_j)}, \quad j = 0, 1, \dots, N, \quad (9)$$

where d_j are

$$d_j = S'_N(x_j) = -c_j N^2 T_N(x_j), \quad ' \equiv \frac{d}{dx} \quad (10)$$

and

$$c_j = 2, \quad \text{for } j = 0, N, \quad c_j = 1 \quad \text{for } 0 < j < N. \quad (11)$$

(Proof) Derivative of $S_N(x)$ with x is

$$S'_N(x) = -N \frac{\cos \theta}{\sin \theta} \sin N\theta - N^2 \cos N\theta$$

Here for $j = 1, \dots, N - 1$, $\sin \theta_j \neq 0$ and $\sin N\theta_j = 0$, so that we obtain $S'_N(x_j) = -N^2 T_N(x_j)$. While $\sin \theta_j = 0$ and $\sin N \times \theta_j = 0$ for $j = 0, N$. Therefore S'_N includes $0/0$, so that we apply the L'Hopital theorem for the first term of the right hand side

$$S'_N(x_j) = S'_N(\theta = 0 \text{ or } \pi) = -N \frac{\cos \theta}{\sin \theta} \sin N\theta - N^2 \cos N\theta$$

$$\stackrel{\text{L'Hopital}}{=} -N \frac{-\sin \theta \sin N\theta + N \cos \theta \cos N\theta}{\cos \theta} - N^2 \cos N\theta = -2N^2 T_N(x_j)$$

3 Derivation of Chebyshev differentiation matrix

Consider Gauss-Chebyshev-Lobatto points (or Chebyshev points, for short) in the $x \in [-1, 1]$ defined by

$$x_j = \cos \theta_j = \frac{\pi j}{N}, \quad j = 0, 1, \dots, N. \quad (12)$$

Given a grid function u defined on the Chebyshev points, we obtain a discrete derivative w in two steps:

- Let p be the unique polynomial of degree $\leq N$ with $p(x_j) = u_j, 0 \leq j \leq N$.
- Set $w_j = p'(x_j)$.

This operation is linear, so it can be represented by multiplication by an $(N + 1) \times (N + 1)$ matrix, which we shall denote by D_N :

$$w_i = (D_N)_{ij} \psi_j \quad (13)$$

Here N is an arbitrary positive integer, even or odd. And, $(D_N)_{ij}$ represents the (i, j) elements of the matrix D_N .

In order to derive the matrix D_N , consider the interpolation polynomial (1) and the interpolation coefficients (9). From the derivative $dp(x)/dx = u(x_j)d\phi_j(x)/dx$ we get

$$(D_N)_{ij} = \frac{1}{d_j} \left[\frac{d}{dx} \phi_j(x) \right]_{x=x_i}. \quad (14)$$

Considering eqn. (9) we obtain

$$\begin{aligned} \frac{d}{dx} \phi_j(x) = \frac{1}{(x - x_j)^2} \left\{ \left[-2x \frac{d}{dx} T_N(x) + (1 - x^2) \frac{d^2}{dx^2} T_N(x) \right] (x - x_j) \right. \\ \left. - (1 - x^2) \frac{d}{dx} T_N(x) \right\}, \quad j = 0, 1, \dots, N. \end{aligned} \quad (15)$$

(I) Non-diagonal elements : $1 < i < N, 1 < j < N, i \neq j$
if we put $x = x_i$ in eqn.(15), we obtain

$$(D_N)_{ij} = \frac{1}{d_j} \frac{1}{x_i - x_j} (1 - x_i^2) \frac{d^2}{dx^2} T_N(x_i), \quad (16)$$

where we used the relation $-2x_i dT_N(x_i)/dx = 0$ in the bracket []. That is $\theta_i = i\pi/N, \sin \theta_i \neq 0$

$$\left. -2x \frac{d}{dx} T_N(x) \right|_{x=x_i} = -2 \cos \theta_i \frac{-N \sin i\pi}{-\sin \theta_i} = 0$$

Similarly this relation was applied for the second term of the ordinary differential equation of Chebyshev polynomial

$$(1 - x^2) \frac{d^2}{dx^2} T_n(x) - x \frac{d}{dx} T_n(x) + n^2 T_n(x) = 0, \quad (17)$$

then we get the following relation:

$$(1 - x_i^2) \frac{d^2}{dx^2} T_N(x_i) = -N^2 T_N(x_i). \quad (18)$$

Substituting this into eqn.(16) we obtain

$$(D_N)_{ij} = \frac{d_i}{d_j} \frac{1}{x_i - x_j} = \frac{c_i T_N(x_i)}{c_j T_N(x_j)} \frac{1}{x_i - x_j}. \quad (19)$$

Considering $T_N(x_i) = \cos[N(i\pi)/N] = \cos i\pi = (-1)^i$ and (11), we get

$$(D_N)_{ij} = \frac{c_i (-1)^{i+j}}{c_j x_i - x_j}, \quad c_i = \begin{cases} 2 & \text{for } i = 0 \text{ or } N \\ 1 & \text{otherwise} \end{cases} \quad (20)$$

(II) Diagonal elements ($i = j$) $0 < i, j < N$

When $x \rightarrow x_j$, the first derivative (15)

$$\left. \frac{d}{dx} \phi_j(x) \right|_{x \rightarrow x_j} = \frac{1}{(x - x_j)^2} \left\{ [Y(x)] (x - x_j) - (1 - x^2) \frac{d}{dx} T_N(x) \right\} \Big|_{x \rightarrow x_j}$$

becomes 0/0 because $(1 - x_j^2) dT_N(x_j)/dx = 0$. Where, we defined $Y(x) = -2x dT_N(x)/dx + (1 - x^2) d^2 T_N(x)/dx^2$, while $x \rightarrow x_j$, $Y(x_j) \neq 0$. We can apply the L'Hopital theorem to the above derivative and get

$$\begin{aligned} \left. \frac{d}{dx} \phi_j(x) \right|_{x \rightarrow x_j} &= \frac{1}{2(x - x_j)} \left\{ -2x T'_N + (1 - x^2) T''_N \right. \\ &\quad \left. + (x - x_j) [-2T'_N - 2x T''_N - 2x T''_N + (1 - x^2) T'''_N] + 2x T'_N - (1 - x^2) T''_N \right\} \\ &= \frac{1}{2(x - x_j)} \left\{ (x - x_j) [-2T'_N - 4x T''_N + (1 - x^2) T'''_N] \right\} \\ &= \frac{1}{2} \left\{ -2T'_N - 4x T''_N + (1 - x^2) T'''_N \right\}, \quad (21) \end{aligned}$$

so that the diagonal elements of the Chebyshev differentiation matrix are

$$(D_N)_{jj} = -\frac{1}{2d_j} \left\{ 2T'_N(x_j) + 4x_j T''_N(x_j) - (1 - x_j^2) T'''_N(x_j) \right\}. \quad (22)$$

Because of $j \neq 0, N$, $\sin \theta_j \neq 0$, then $T'_N(x_j) = 0$. And from eqn. (17)

$$-(1-x^2)T_N'''(x) = -3xT_N''(x) + (N^2-1)T_N'(x).$$

Considering $T'_N(x_j) = 0$, we substitute this relation into eqn. (22) we obtain

$$(D_N)_{jj} = -\frac{1}{2d_j}x_jT_N''(x_j).$$

Moreover for $T_N''(x_j)$ and making use of (18), the diagonal elements are derived as follows:

$$(D_N)_{jj} = -\frac{-x_jN^2T_N(x_j)}{2d_j(1-x_j^2)} = \frac{-x_j}{2(1-x_j^2)}. \quad (23)$$

(III) $i = 0, j = 0$ or $i = N, j = N$

Because $x_j = 1$ for $j = 0$ and $x_j = -1$ for $j = N$, then the last term of the right hand side of (22) vanishes. And we know

$$T_N(1) = 1, \quad T_N(-1) = (-1)^N, \quad T'_N(1) = N^2, \quad T'_N(-1) = -(-1)^N N^2$$

and also

$$T_N''(1) = \frac{(N^2-1)N^2}{3}, \quad T_N''(-1) = -(-1)^N \frac{(N^2-1)N^2}{3}.$$

Therefore the numerator and denominator of eqn.(22) are

$$i = 0, j = 0 : \quad 2T'_N(1) + 4T_N''(1) = \frac{2N^2(2N^2+1)}{3}, \quad 2d_0 = -4N^2T_N(1)$$

$$i = N, j = N : \quad 2T'_N(-1) + 4T_N''(-1) = -(-1)^N \frac{2N^2(2N^2+1)}{3},$$

$$2d_0 = -4N^2T_N(-1),$$

so that finally we get

$$(D_N)_{00} = \frac{2N^2+1}{6}, \quad (D_N)_{NN} = -\frac{2N^2+1}{6}. \quad (24)$$

Derivation of $T_N''(\pm 1)$:

Ordinary differentiation equation for Chebyshev polynomial in (V) we used

$$-(1-x^2)T_N'''(x) = -3xT_N''(x) + (N^2-1)T_N'(x).$$

By using for $x = 1$ in above equation, we obtain

$$T_N''(1) = \frac{(N^2-1)}{3}T'_N(1) = \frac{(N^2-1)N^2}{3}.$$

For $T_N''(-1)$, we derive similarly.

References

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